Effect of Normal Force Dispersion on the Mobility of Wheeled Robots Operating on Soft Soil

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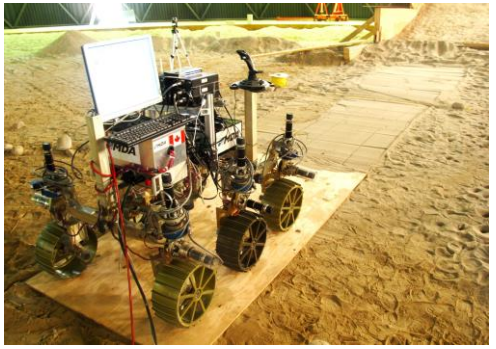
- The effect of the normal force distribution on the traction capability at wheel-terrain contact is the subject of the paper
- The study is extended to the case of wheeled robots operating on soft soil
- A performance indicator based on the distribution of normal load among the wheels of robot is defined
- Conditions under which the change of this indicator has significant effect on rover mobility are identified



Rover Chassis Prototype used for the experiments